

THE EXTENSIONAL CONSTRAINT

ACP dissertation award

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3 August 2022

Advisors:

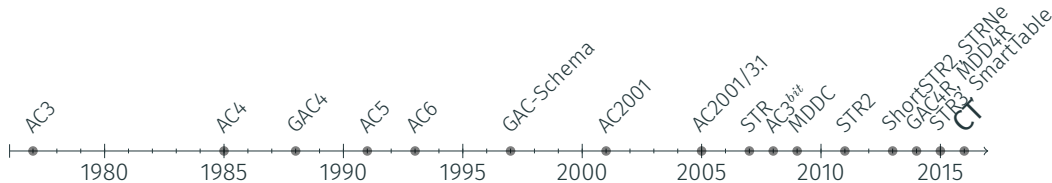
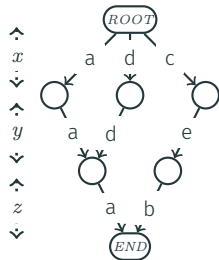
- Pierre Schaus
- Christophe Lecoutre



	x	y	z
τ_1	a	a	a
τ_2	d	d	a
τ_3	c	e	b
\vdots	\vdots	\vdots	\vdots

Tables are one of the oldest most used CP constraints

MDDs are equivalent to tables

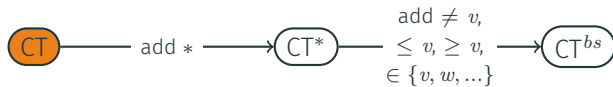



2016 : New algorithm! Compact-Table [CP2016], based on bitwise operations, completely outperformed existing algorithms

CT

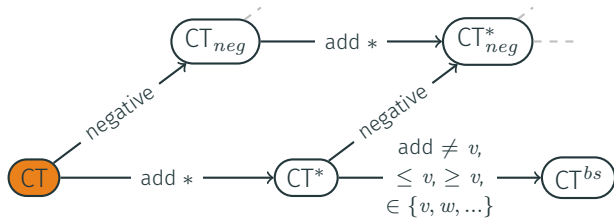
State of the art


Published



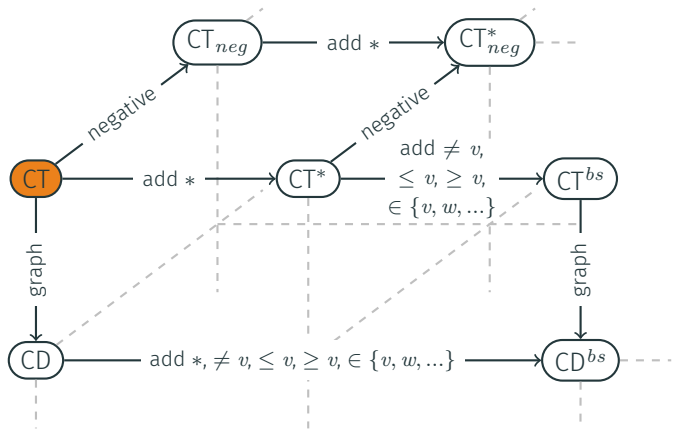
 State of the art

 Published



 State of the art

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● State of the art ○ Published

COMPACT-TABLE

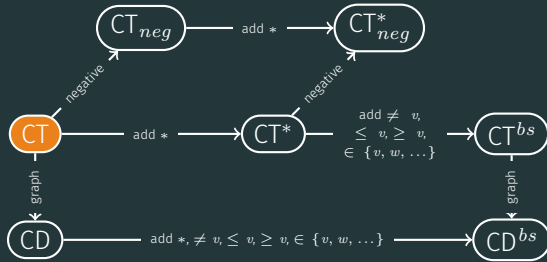


Table				τ_1	τ_2	τ_3	τ_4	τ_5	τ_6	τ_7	τ_8	
	x_1	x_2	x_3	currTable								
				1	1	1	1	1	1	1	1	
				supports								
τ_1	a	c	a	$[x_1, a]$	1	0	1	0	0	0	1	0
τ_2	b	b	b	$[x_1, b]$	0	1	0	0	1	0	0	1
τ_3	a	c	b	$[x_1, c]$	0	0	0	1	0	1	0	0
τ_4	c	a	b	$[x_2, a]$	0	0	0	1	0	0	1	0
τ_5	b	c	b	$[x_2, b]$	0	1	0	0	0	1	0	1
τ_6	c	b	c	$[x_2, c]$	1	0	1	0	1	0	0	0
τ_7	a	a	b	$[x_3, a]$	1	0	0	0	0	0	0	0
τ_8	b	b	c	$[x_3, b]$	0	1	1	1	1	0	1	0
				$[x_3, c]$	0	0	0	0	0	1	0	1

Reversible Sparse Bitset
 Precomputed Bitsets

Table				$\tau_1 \ \tau_2 \ \tau_3 \ \tau_4 \ \tau_5 \ \tau_6 \ \tau_7 \ \tau_8$									
	x_1	x_2	x_3	currTable									
				1	1	1	1	1	1	1	1	} Reversible Sparse Bitset	
τ_1	a	c	a	supports									
τ_2	b	b	b	$[x_1, a]$	1	0	1	0	0	0	1	0	} Precomputed Bitsets
τ_3	a	c	b	$[x_1, b]$	0	1	0	0	1	0	0	1	
τ_4	c	a	b	$[x_1, c]$	0	0	0	1	0	1	0	0	
τ_5	b	c	b	$[x_2, a]$	0	0	0	1	0	0	1	0	
τ_6	c	b	c	$[x_2, b]$	0	1	0	0	0	1	0	1	
τ_7	a	a	b	$[x_2, c]$	1	0	1	0	1	0	0	0	
τ_8	b	b	c	$[x_3, a]$	1	0	0	0	0	0	0	0	
				$[x_3, b]$	0	1	1	1	1	0	1	0	
				$[x_3, c]$	0	0	0	0	0	1	0	1	

Classical update

Δ_x {	supports[x,b]	0	0	0	1
	supports[x,d]	1	0	0	0
	supports[x,f]	0	1	0	0
		$\sim \cup =$			
mask	0	0	1	0	
		\cap			
old currTable	1	1	1	0	
		=			
new currTable	0	0	1	0	

Reset update

$dom(x)$ {	supports[x,a]	1	0	0	0
	supports[x,c]	0	1	0	0
	supports[x,e]	0	0	0	1
		$\cup =$			
mask	1	1	0	1	
		\cap			
old currTable	1	0	1	0	
		=			
new currTable	1	0	0	0	

currTable	0	1	1	0
-----------	---	---	---	---

 \cap

supports[x,a]	1	1	0	0
---------------	---	---	---	---

 $=$

intersection	0	1	0	0
--------------	---	---	---	---

 \Downarrow

not empty

 \Downarrow
 $a \in \text{dom}(x)$

currTable	0	1	1	0
-----------	---	---	---	---

 \cap

supports[x,b]	0	0	0	1
---------------	---	---	---	---

 $=$

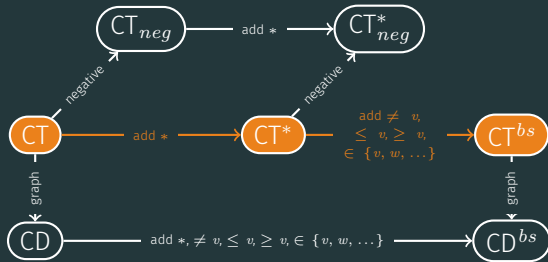
intersection	0	0	0	0
--------------	---	---	---	---

 \Downarrow

empty

 \Downarrow
 $\text{dom}(x) \setminus \{b\}$

1ST DIMENSION: FROM GROUND TABLES TO SMART TABLES

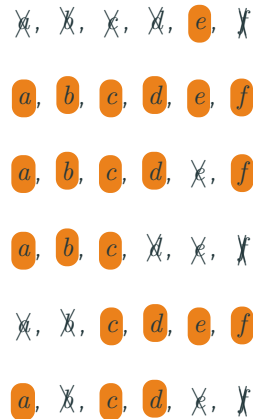


A Basic Smart Table

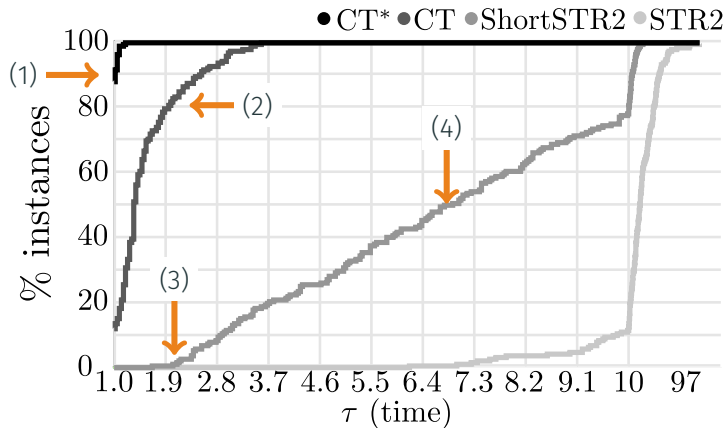
contains unary Smart Elements representing multiples values

	x	y	z
τ_1	*	*	$\in \{a, b\}$
τ_2	$\neq a$	c	$\leq a$
τ_3	b	*	*
τ_4	$\geq c$	$\neq b$	a
	\vdots	\vdots	\vdots

- single value: e
- universal value: *
- exclusion: $\neq e$
- upper bound: $\leq c$
- lower bound: $\geq c$
- set: $\in \{a, c, d\}$



$$\begin{array}{r}
 \Delta^x \left\{ \begin{array}{l}
 \text{supports}^*[x,b] \\
 \text{supports}^*[x,d] \\
 \text{supports}^*[x,f]
 \end{array} \right.
 \end{array}
 \begin{array}{c}
 * \\
 \downarrow \\
 \begin{array}{|c|c|c|c|}
 \hline
 0 & 0 & 0 & 1 \\
 \hline
 0 & 0 & 0 & 0 \\
 \hline
 0 & 1 & 0 & 0 \\
 \hline
 \end{array} \\
 \sim \cup = \\
 \text{mask} \begin{array}{|c|c|c|c|}
 \hline
 1 & 0 & 1 & 0 \\
 \hline
 \end{array} \\
 \cap \\
 \text{old currTable} \begin{array}{|c|c|c|c|}
 \hline
 1 & 1 & 1 & 0 \\
 \hline
 \end{array} \\
 = \\
 \text{new currTable} \begin{array}{|c|c|c|c|}
 \hline
 1 & 0 & 1 & 0 \\
 \hline
 \end{array}
 \end{array}$$



Complexity of CT*:

same as CT ($\mathcal{O}(rd_w^t)$)

(1) CT* best 90% of the time

(2) CT requires $< 2\times$ time on 80%

(3) ShortSTR2 needs $> 2\times$ time

(4) ShortSTR2 needs $> 7\times$ time on 50%

600 instances, 20 variables, domain size from 5 to 7, 40 random tables by instances, arity of 6 or 7, tightness [0.5%;2%], 1, 5, 10 or 20 % of short tuples

$$|dom(x)| == 0$$

Trivial!
Handled by variable x

$$|dom(x)| == 1$$

$|\Delta_x| \geq |dom(x)|$ always true!
ResetUpdate(x) used
and already working!

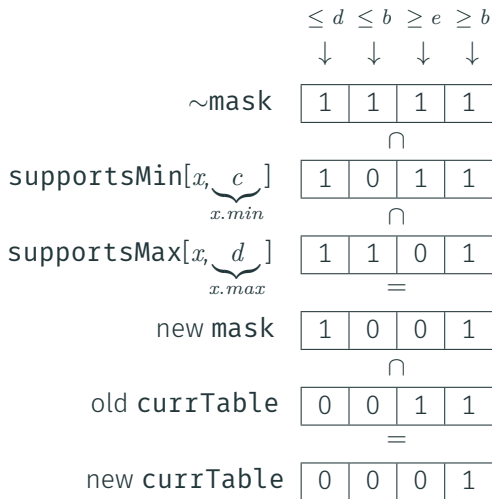
$$|dom(x)| > 1$$

If $|\Delta_x| < |dom(x)|$

Tuple always valid!
At least one valid value
supports* $[x][\tau] = 0$

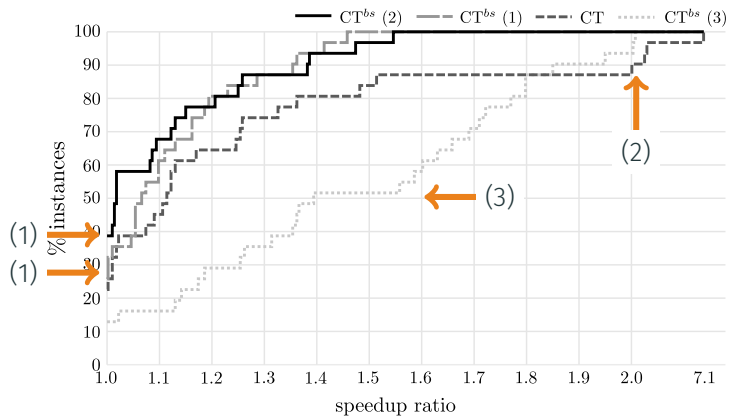
If $|\Delta_x| \geq |dom(x)|$

ResetUpdate(x) used
and already working!



$ dom(x) $	sets		structured sets
1	$\{a\}$	1	* 1
2	$\{a\}, \{b\}, \{a, b\}$	3	$a, b, *$ 3
3	$\{a\}, \{b\}, \{c\}, \{a, b\},$ $\{a, c\}, \{b, c\}, \{a, b, c\}$	7	$a, b, c, \neq a,$ $\neq b, \neq c, *$ 7
4	$\{a\}, \{b\}, \dots, \{a, b\}, \{a, c\},$ $\{a, d\}, \{b, c\}, \{b, d\}, \{c, d\},$ $\{a, b, c\}, \dots, \{a, b, c, d\}$	15	$a, b, c, d,$ $\leq b, \geq c, \neq a,$ $\neq b, \neq c, \neq d, *$ 11
5	$\{a\}, \{b\}, \dots, \{a, b\}, \{a, c\}, \{a, d\}, \{a, e\},$ $\{b, c\}, \{b, d\}, \{b, e\}, \{c, d\}, \{c, e\},$ $\{a, b, c\}, \{a, b, d\}, \{a, b, e\}, \{a, c, d\},$ $\{a, c, e\}, \dots, \{a, b, c, d\}, \dots, \{a, b, c, d, e\}$	31	a, b, c, d, e $\leq b, \leq c, \geq c,$ $\geq d, \neq a, \neq b,$ $\neq c, \neq d, \neq e, *$ 15

- `supports[x,v]`: supports value v
- `supports*[x,v]`: supports only value v
- `supportsMin[x,v]`: supports at least one value $\geq v$
- `supportsMax[x,v]`: supports at least one value $\leq v$

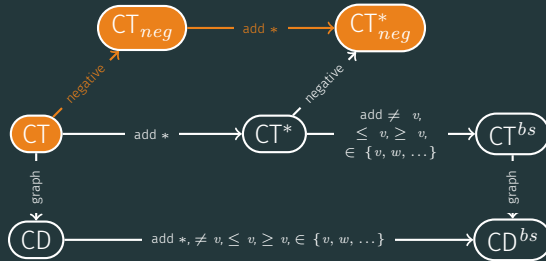


Complexity of CT^{bs}:
same as CT ($\mathcal{O}(rd\frac{t}{w})$)

- (1) CT^{bs} best on 40 + 30%
- (2) CT needs $< 2\times$ for 88%
- (3) Overhead due to Set only

XCSP3 instances with only tables, transformed into basic smart table with at least 10% compression (1) with only $\leq v$ and $\geq v$, (2) with $\leq v$ and $\geq v +$ post processing to add $*$ and $\neq v$, (3) with elements treated as simple sets

2ND DIMENSION: FROM POSITIVE TO NEGATIVE TABLES



Negative Table

	x_1	x_2	x_3
τ_1	a	c	a
τ_2	b	b	b
τ_3	a	c	b
τ_4	c	a	b
τ_5	b	c	b
τ_6	c	b	c
τ_7	a	a	b
τ_8	b	b	c

 τ_1 τ_2 τ_3 τ_4 τ_5 τ_6 τ_7 τ_8

currTable

1	1	1	1	1	1	1	1
---	---	---	---	---	---	---	---

dangerous supports

$[x_1, a]$	1	0	1	0	0	0	1	0
$[x_1, b]$	0	1	0	0	1	0	0	1
$[x_1, c]$	0	0	0	1	0	1	0	0
$[x_2, a]$	0	0	0	1	0	0	1	0
$[x_2, b]$	0	1	0	0	0	1	0	1
$[x_2, c]$	1	0	1	0	1	0	0	0
$[x_3, a]$	1	0	0	0	0	0	0	0
$[x_3, b]$	0	1	1	1	1	0	1	0
$[x_3, c]$	0	0	0	0	0	1	0	1

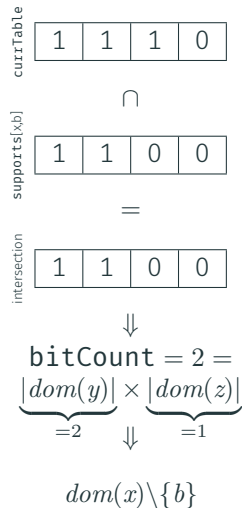
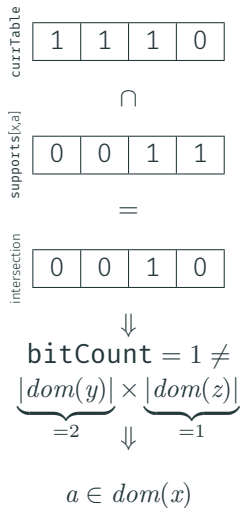
Reversible
Sparse Bitset

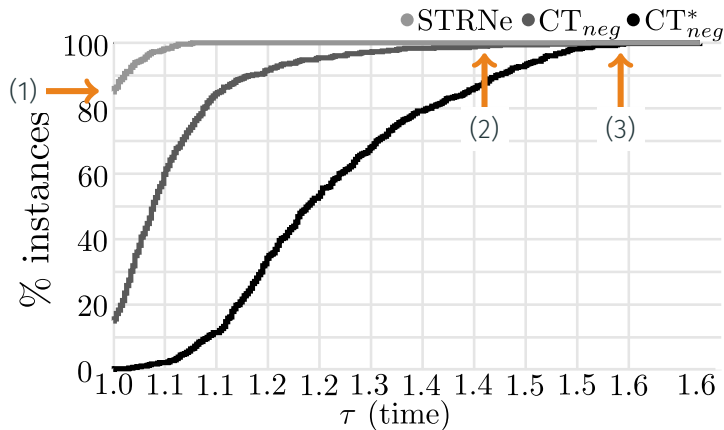
Precomputed Bitsets

Hypothesis

No duplicate!

No overlap!





Complexity of CT_{neg}:

CT's complexity × complexity of bitcount ($\mathcal{O}(rd_{\frac{t}{w}}k)$)

Complexity of CT_{neg}^{*}:

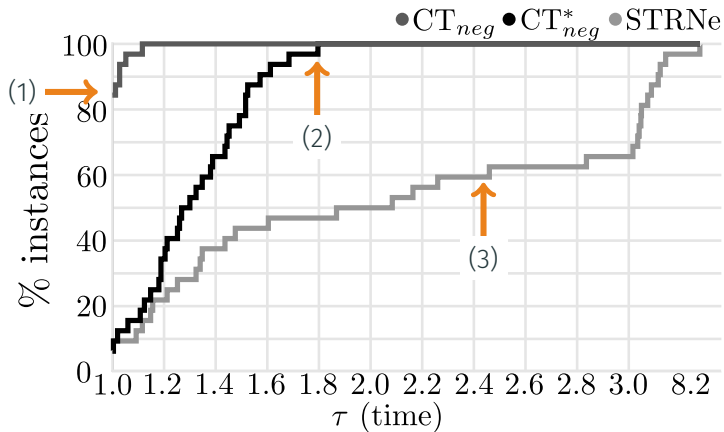
CT_{neg}'s complexity, using t' the # of tuples with dummy ones ($\mathcal{O}(rd_{\frac{t'}{w}}k)$)

(1) STRNe best 85%

(2) CT_{neg} requires max 1.4×

(3) CT_{neg}^{*} requires max 1.6×

600 instances (with high number of solution), 20 variables, domain size from 5 to 7, 40 random tables by instances, arity of 6 or 7, tightness [0.5%;2%], 1, 5, 10 or 20 % of short tuples



Complexity of CT_{neg}:

CT's complexity × complexity of bitcount ($\mathcal{O}(rd_w^t k)$)

Complexity of CT^{*}_{neg}:

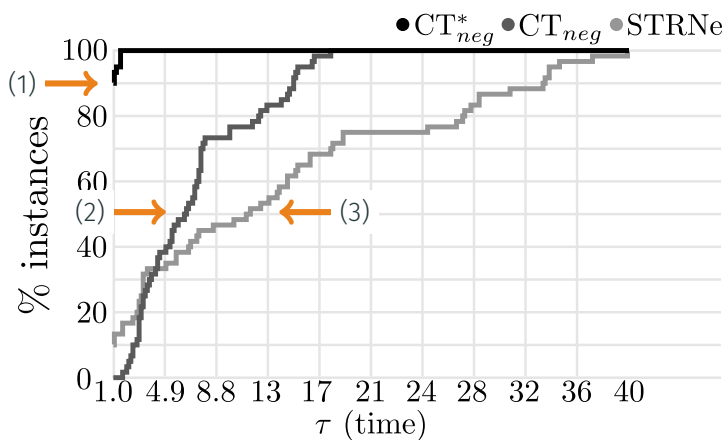
CT_{neg}'s complexity, using t' the # of tuples with dummy ones ($\mathcal{O}(rd_w^{t'} k)$)

(1) CT_{neg} best 85% of the time

(2) < 1.8× for CT^{*}_{neg}

(3) STRNe requires > 2.5× on 40% of instances

45 instances (with low number of solutions), 10 variables, domain size of 5, 40 random tables by instances, arity of 6, tightness 10,... 90%, no short tuples



Complexity of CT_{neg}:

CT's complexity × complexity of bitcount ($\mathcal{O}(rd_w^t k)$)

Complexity of CT_{neg}^{*}:

CT_{neg}'s complexity, using t' the # of tuples with dummy ones ($\mathcal{O}(rd_w^{t'} k)$)

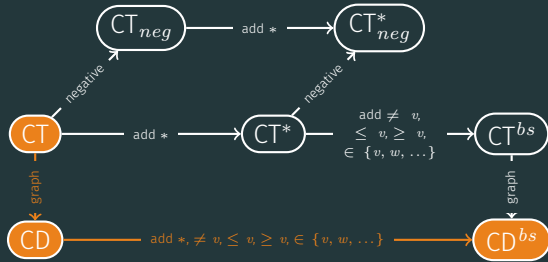
(1) CT_{neg}^{*} best 90% of the time

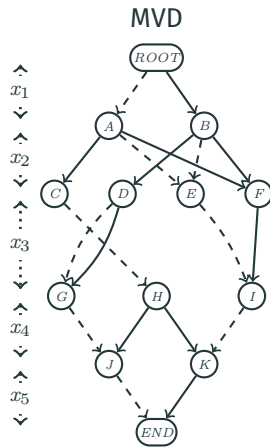
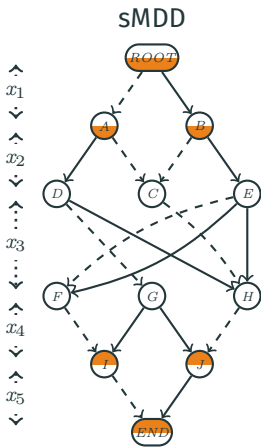
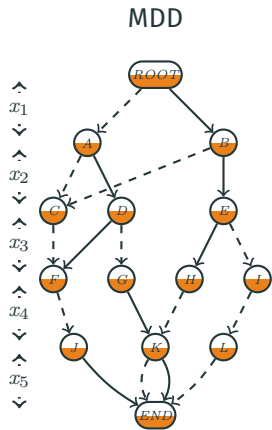
(2) > 6× for 50%

(3) > 11× for 50%

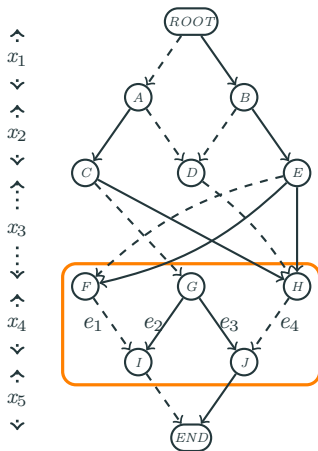
100 instances (with low number of solutions), 3 variables, domain size of 100, 40 random tables by instances, arity of 3, tightness [0.5;2%], 5, 10 or 20 % of short tuples

3RD DIMENSION: FROM TABLES TO GRAPHS

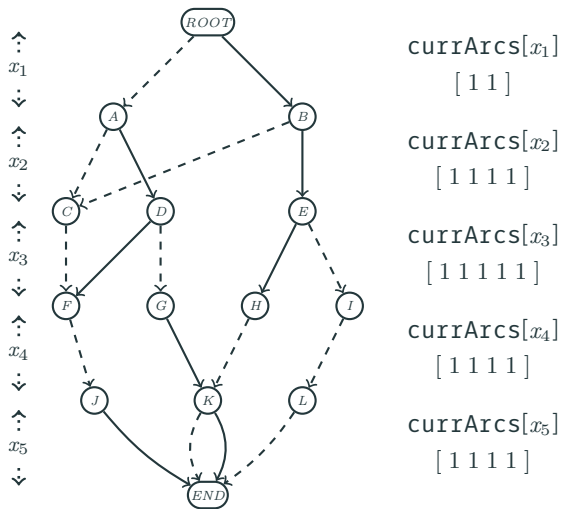


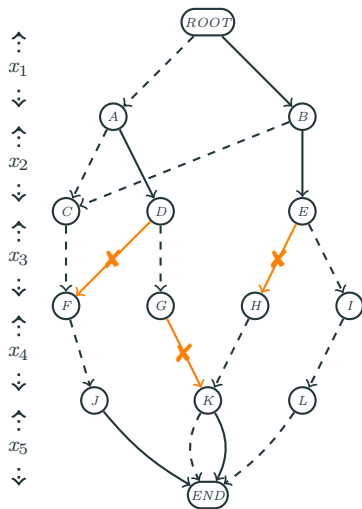


○ in-nd & out-nd ◐ in-nd & out-d ◑ in-d & out-nd



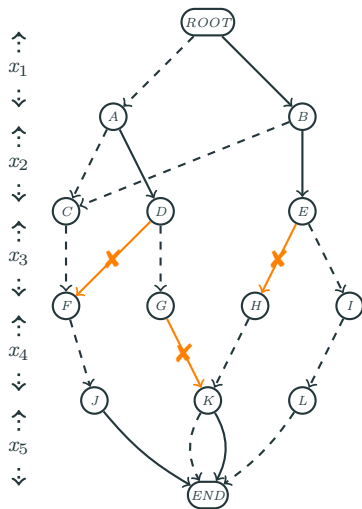
Name	Set	Bit-set
<code>currArcs</code> $[x_4]$	$\{e_1, e_2, e_3, e_4\}$	[1 1 1 1]
<code>supports</code> $[x_4, 0]$	$\{e_1, \cancel{e_2}, \cancel{e_3}, e_4\}$	[1 0 0 1]
<code>arcsT</code> $[G, x_4]$	$\{\cancel{e_1}, e_2, e_3, \cancel{e_4}\}$	[0 1 1 0]
<code>arcsH</code> $[x_4, I]$	$\{e_1, e_2, \cancel{e_3}, \cancel{e_4}\}$	[1 1 0 0]




 $\text{currArcs}[x_1]$
 $[1\ 1]$
 $\text{currArcs}[x_2]$
 $[1\ 1\ 1\ 1]$
 $\text{currArcs}[x_3]$
 $[1\ 1\ 1\ 1\ 1]$
 $\text{currArcs}[x_4]$
 $[1\ 1\ 1\ 1]$
 $\text{currArcs}[x_5]$
 $[1\ 1\ 1\ 1]$

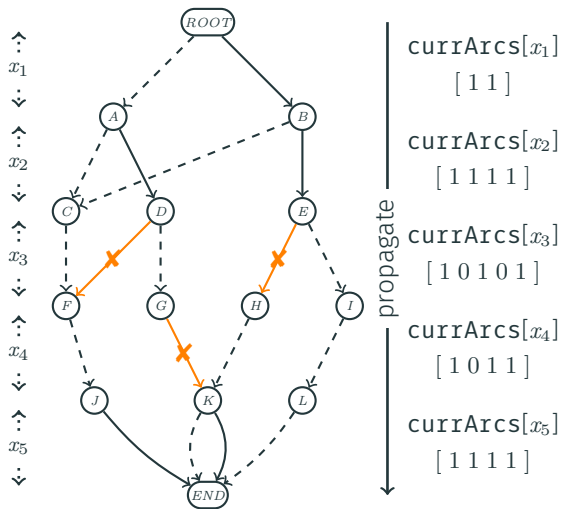
1st step

Direct removal

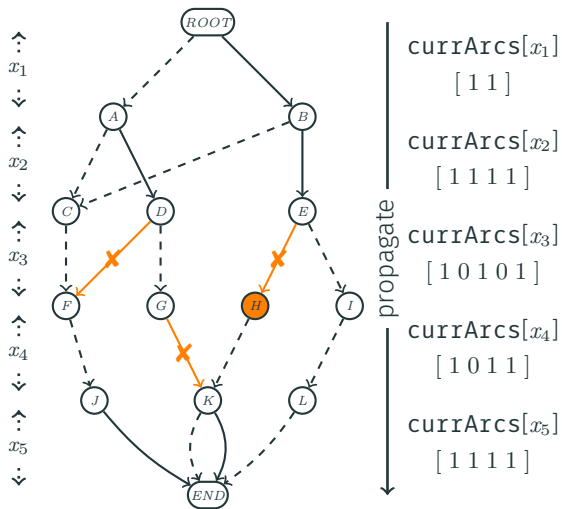

 $\text{currArcs}[x_1]$
 $[1\ 1]$
 $\text{currArcs}[x_2]$
 $[1\ 1\ 1\ 1]$
 $\text{currArcs}[x_3]$
 $[1\ 0\ 1\ 0\ 1]$
 $\text{currArcs}[x_4]$
 $[1\ 0\ 1\ 1]$
 $\text{currArcs}[x_5]$
 $[1\ 1\ 1\ 1]$

1st step

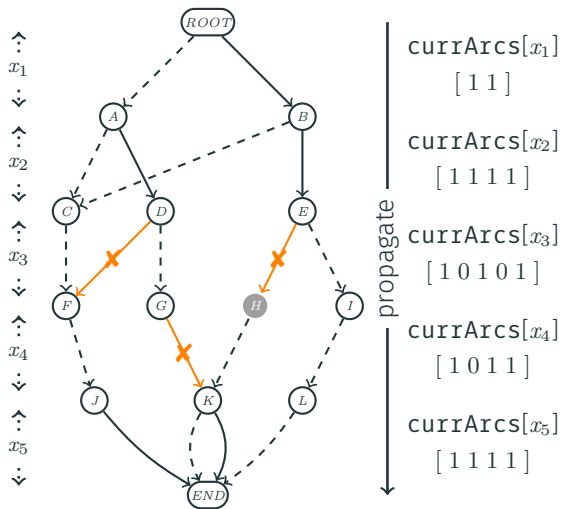
Direct removal



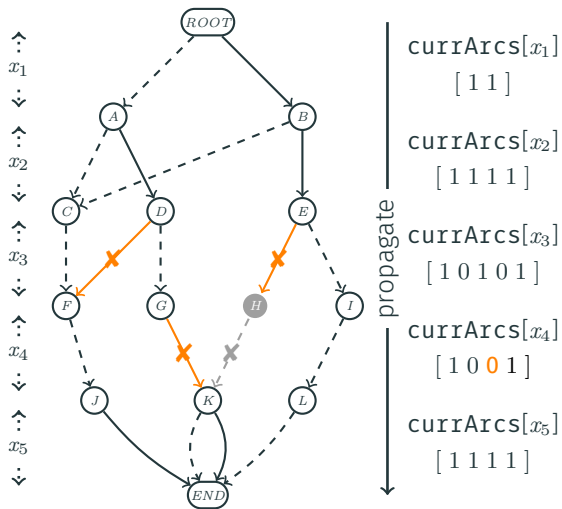
2nd step
Top down



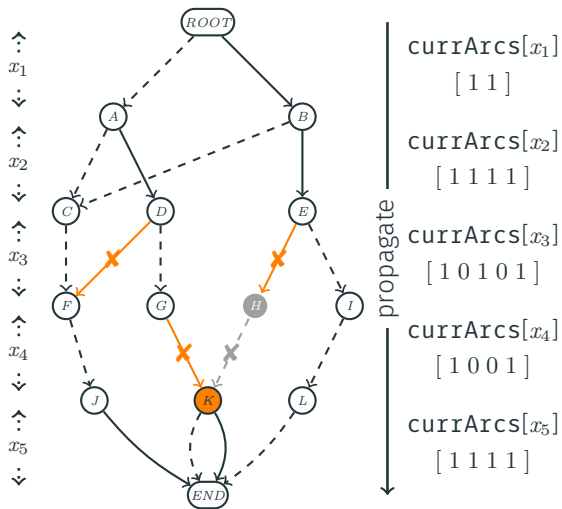
2nd step
Top down



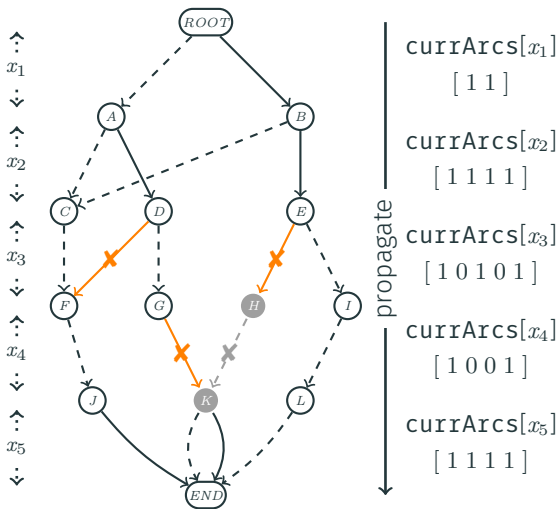
2nd step
Top down



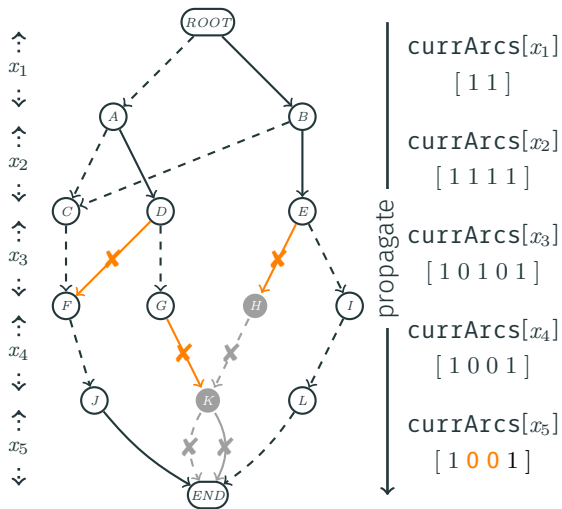
2nd step
Top down



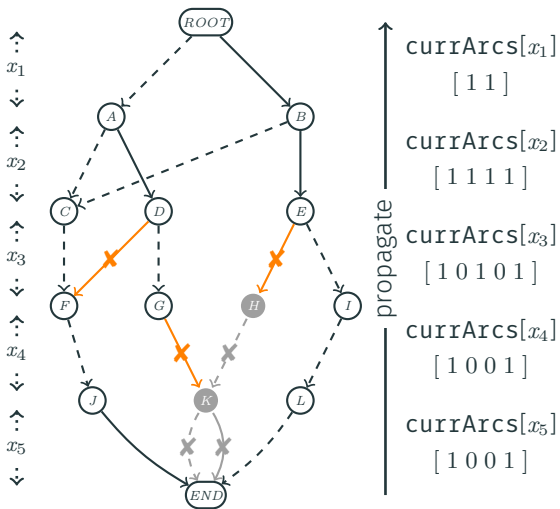
2nd step
Top down



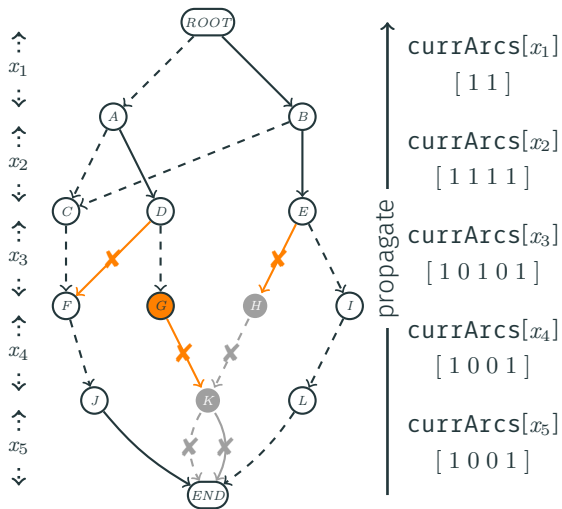
2nd step
Top down



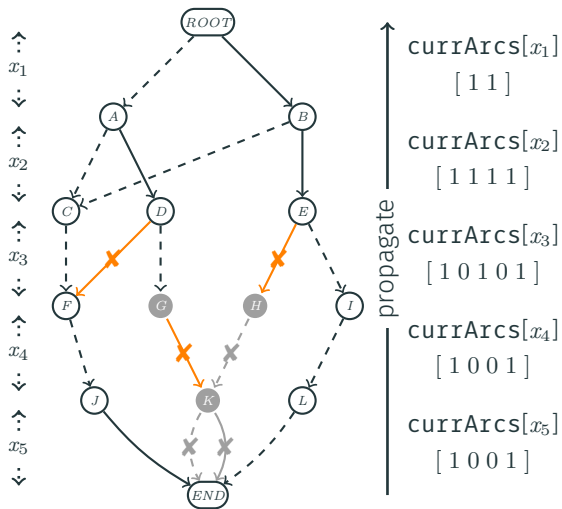
2nd step
Top down



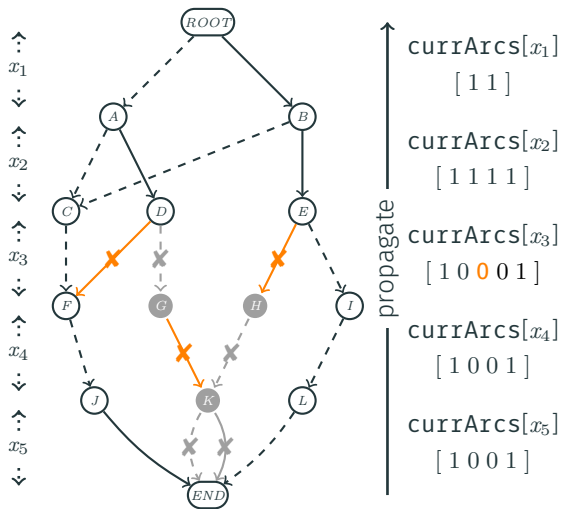
3rd step
Bottom up



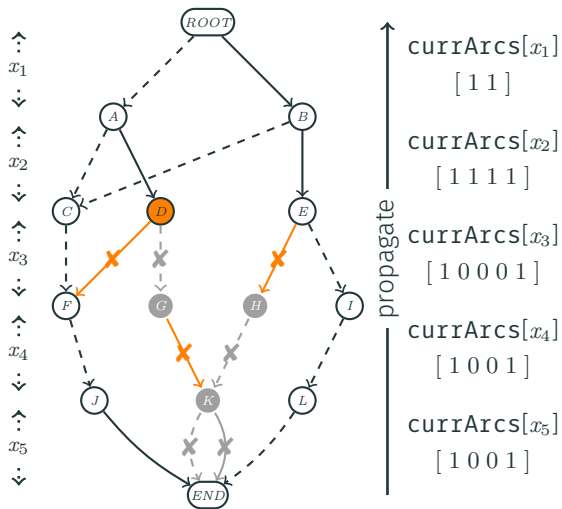
3rd step
Bottom up



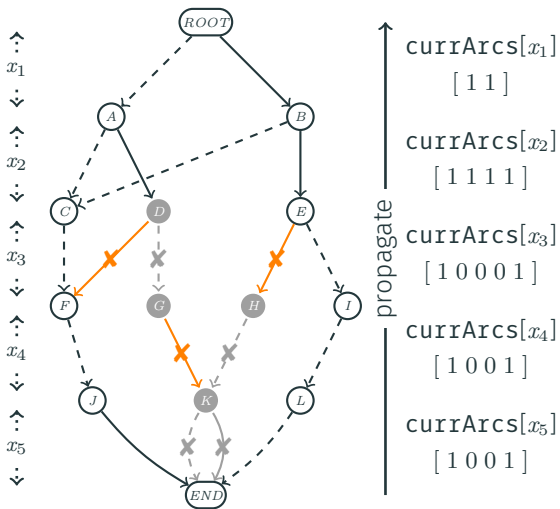
3rd step
Bottom up



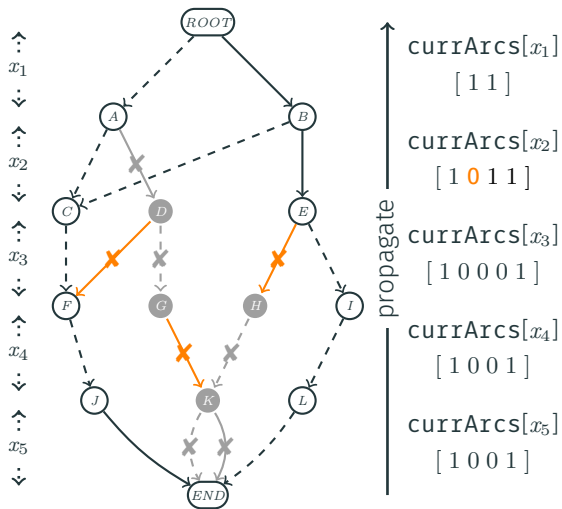
3rd step
Bottom up



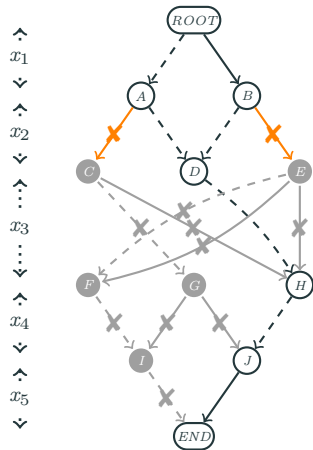
3rd step
Bottom up



3rd step
Bottom up



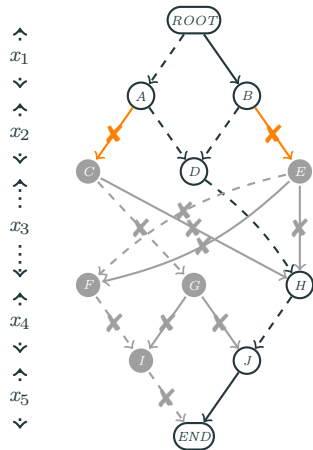
3rd step
Bottom up



$$\Delta_{x_2} = \{1\}$$

x_1	x_2	x_3	x_4	x_5
$\{0, 1\}$	$\{0\}$	$\{0, 1\}$	$\{0, 1\}$	$\{0, 1\}$

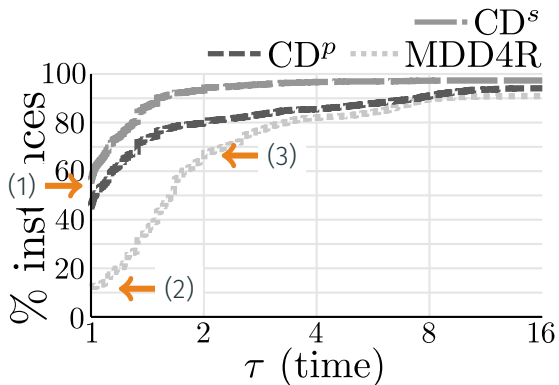
(x, v)	currArcs[x]	supports[x,v]	\cap
$(x_1, 0)$	11	10	10
$(x_1, 1)$	11	01	01
$(x_3, 0)$	001000	101100	001000
$(x_3, 1)$	001000	010011	000000
$(x_4, 0)$	0001	1001	0001
$(x_4, 1)$	0001	0110	0000
$(x_5, 0)$	01	10	00
$(x_5, 1)$	01	01	01



$$\Delta_{x_2} = \{1\}$$

x_1	x_2	x_3	x_4	x_5
$\{0, 1\}$	$\{0\}$	$\{0, \cancel{1}\}$	$\{0, \cancel{1}\}$	$\{\emptyset, 1\}$

(x, v)	currArcs[x]	supports[x,v]	\cap
$(x_1, 0)$	11	10	10
$(x_1, 1)$	11	01	01
$(x_3, 0)$	001000	101100	001000
$(x_3, 1)$	001000	010011	000000
$(x_4, 0)$	0001	1001	0001
$(x_4, 1)$	0001	0110	0000
$(x_5, 0)$	01	10	00
$(x_5, 1)$	01	01	01

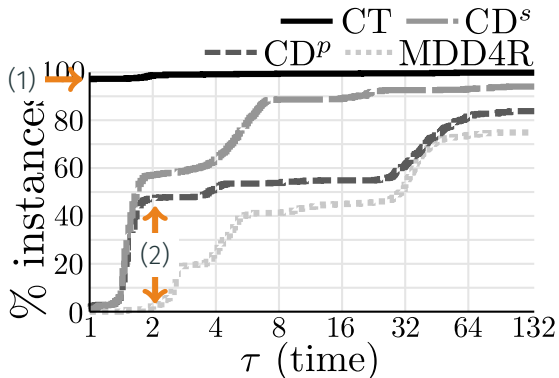


Complexity of CD:

similar to CT
 $(\mathcal{O}(\max(n, d)r\frac{a}{w}))$

- (1) CD gives best results, sMDDs better than MDDs
- (2) MDD4R only best on 12%
- (3) MDD4R requires $> 2\times$ on 35%

XCSP3 instances with only tables, transformed into sMDD or MDD instances only



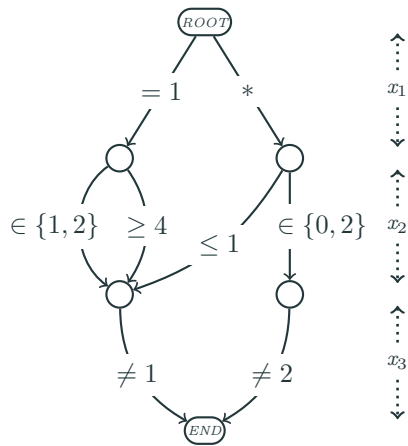
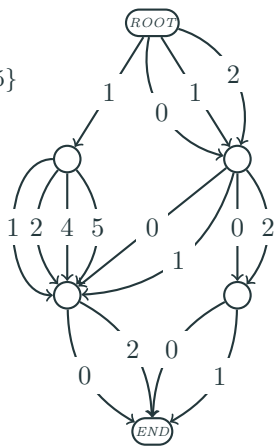
Complexity of CD:

similar to CT
 $(\mathcal{O}(\max(n, d)r\frac{a}{w}))$

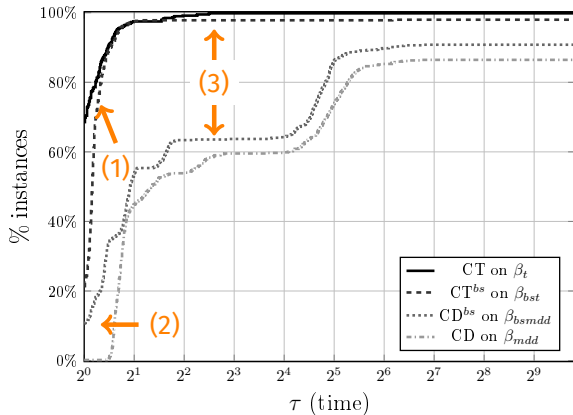
- (1) CT still best 95%
- (2) Reduction of the gap:
 CD^s requires $< 2\times$ for 60%,
 CD^p requires $< 2\times$ for 50%,
 while MDD4R requires $< 2\times$ for 5%

XCSP3 instances with only tables, transformed into sMDD or MDD instances only

Domains
 $x_0 : \{0, 1, 2\}$
 $x_1 : \{0, 1, 2, 3, 4, 5\}$
 $x_2 : \{0, 1, 2\}$



$\uparrow \dots$
 x_1
 $\downarrow \dots$
 $\uparrow \dots$
 x_2
 $\downarrow \dots$
 $\uparrow \dots$
 x_3
 $\downarrow \dots$

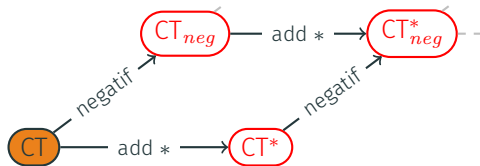


- (1) CT and CT^{bs} still dominating
- (2) CD^{bs} becomes efficient when compression is high
- (3) gap reduced

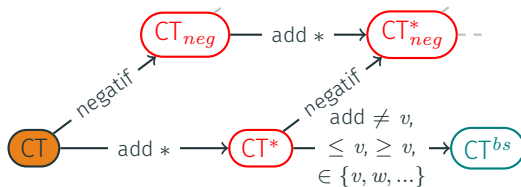
XCSP3 instances with only tables, transformed into bs-table, MDD and bs-MDD instances only

CONCLUSION



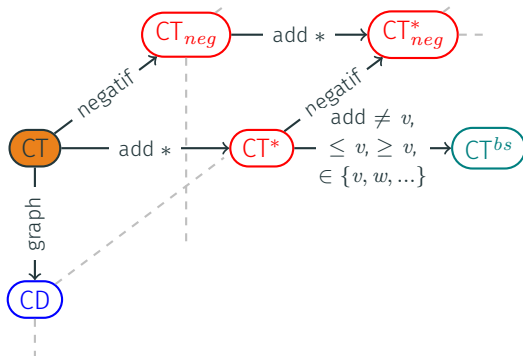


H. Verhaeghe, C. Lecoutre and P. Schaus. **Extending Compact-Table to Negative and Short Tables.** AAI17



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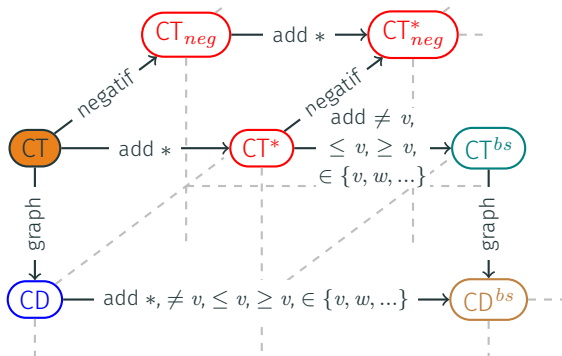
H. Verhaeghe, C. Lecoutre, Y. Deville and P. Schaus. **Extending Compact-Table to Basic Smart Tables.** CP2017



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H. Verhaeghe, C. Lecoutre, P. Schaus. **Extending Compact-Diagram to Basic Smart Multi-Valued Variable Diagrams**. CPAIOR19

- Increasing non-determinism in diagrams
- Closing the gap between diagrams and tables propagators
- Direct use of compressed tables and non-deterministic diagrams in applications

Thank you for listening!

Any questions?

<https://hverhaeghe.bitbucket.io/>